Algorithms for Data Structures: Search for Games

> Phillip Smith 27/11/13

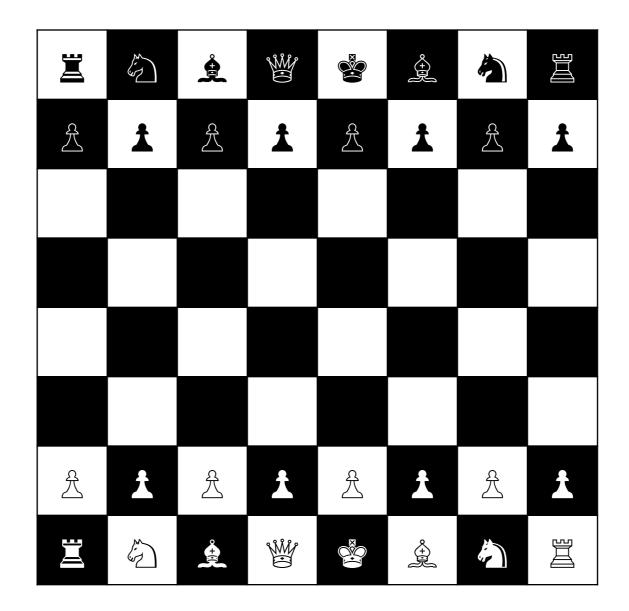
## Search for Games

- Following this lecture you should be able to:
  - Understand the search process in games
  - How an AI decides on the best moves to make, given a search space
  - Implement various evaluation functions
  - How to prune a search tree to make sure irrelevant paths aren't followed

# Playing Games with Al

- Games such as chess offer pure, abstract competition, which makes them popular for AI research
- The states of a game such as chess are easy to represent
- Actions on the states are restricted to a small number of fairly well-defined actions
- Game playing is an idealisation of worlds in which hostile agents act to diminish one's well being, within this world

#### State Representation: Chess



Shannon(1950), Programming a Computer for Playing Chess, Philosophical Magazine 41(314)

# Why is chess important to AI?

- A chess-playing machine would be an existence of the proof of a machine doing something thought to require intelligence
- Simplicity of rules combined with the programmable states of the world means that this can be represented as a search problem through a space of <u>all possible</u> <u>game positions</u>
- The representation of the game can be correct in every possible way, unlike other similar problems e.g fighting a war

# Why is chess important to AI?

- The introduction of an opponent brings <u>uncertainty</u> to the search space
  - Opponent will attempt to make the best move possible
- Search for games is hard to solve
- Chess has an average branching factor of 35
- Games go on to roughly 50 moves per player
  - Search tree has around 35<sup>100</sup> nodes
- The uncertainty in this is choosing the best move given all combinations
  - We can't search through all possible solutions in a reasonable time
- We must guess based upon past experiences

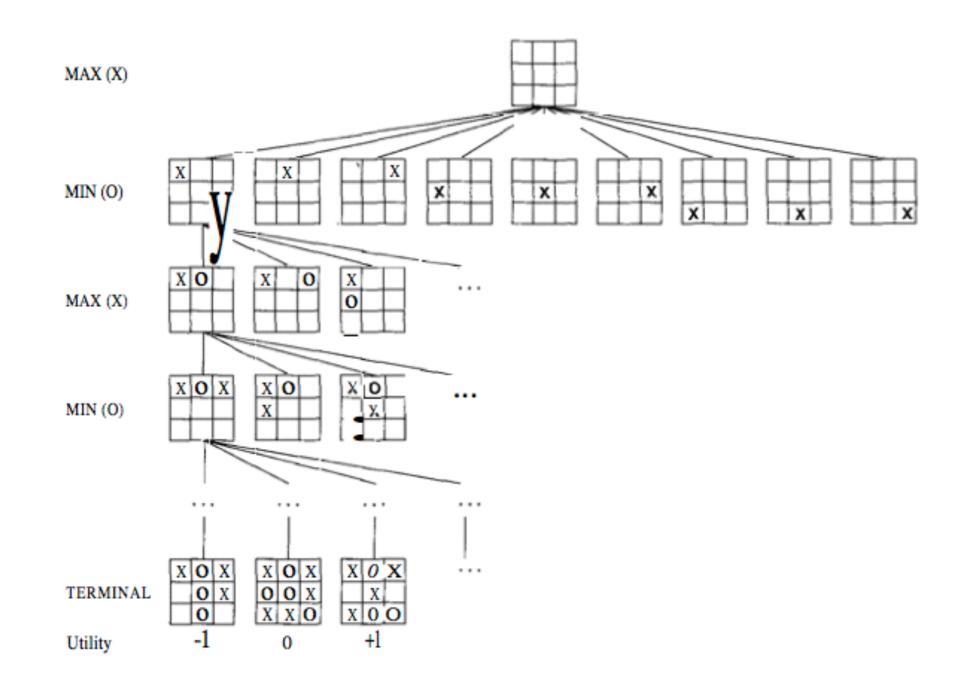
#### Decision Making in Two-Player Games

- Consider a two player game, with players named MAX & MIN
- MAX moves first, and take turns moving until the game is over
- At the end of the game, point are awarded to the winning player
- We can define a game as a search problem as follows:
  - Initial state: Board position and whose move it is
  - <u>Set of actions:</u> Legal moves a player can make
  - <u>Terminal test:</u> Check if the game is over
  - <u>Set of utility functions</u>: Numeric value of the outcome of the game: +1, 0, -1

# Strategy

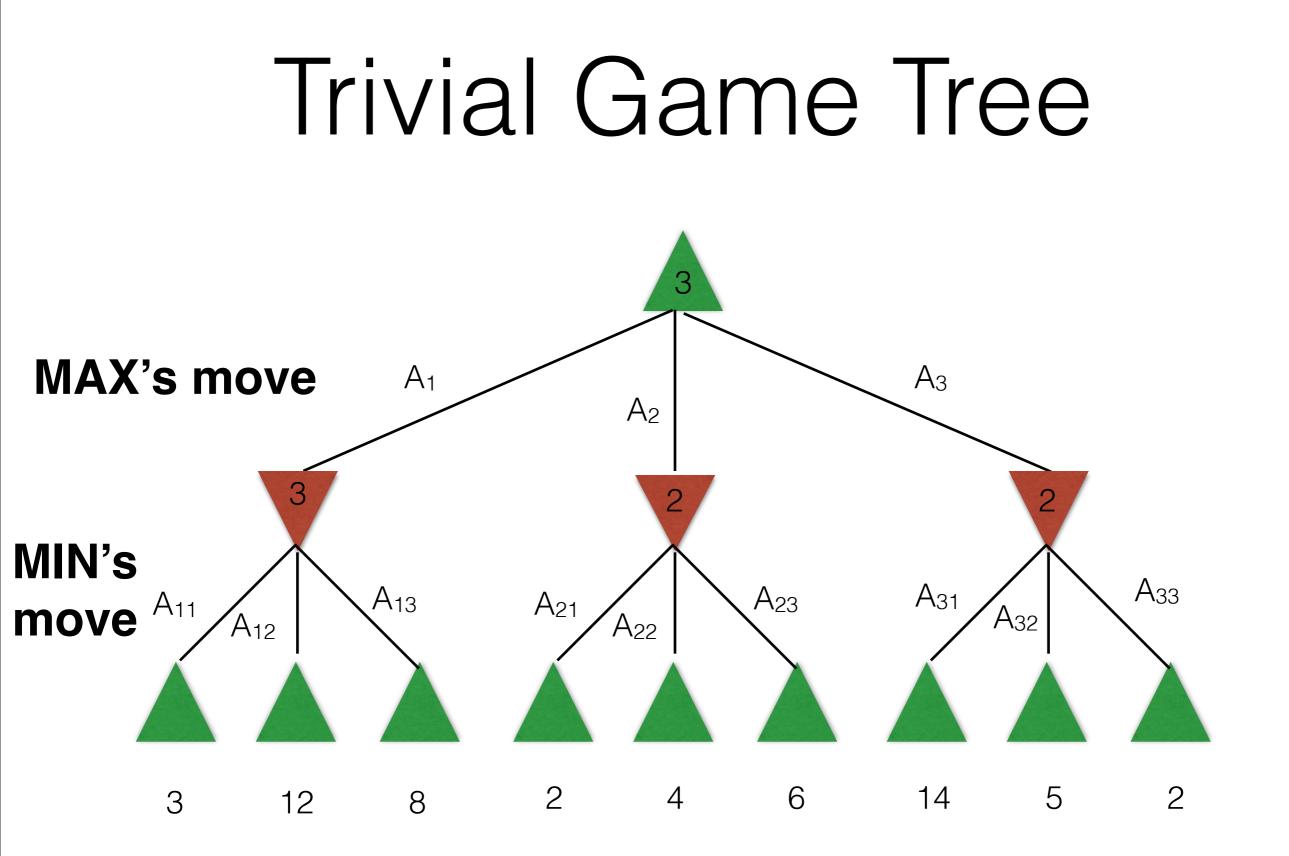
- In normal search, MAX would search for moves that lead to a winning state
- MIN however will interfere with this
- MAX requires a strategy to win, regardless of MIN's actions
- MAX will attempt to make the correct move corresponding to the actions of MIN

## Noughts and Crosses



# Minimax Algorithm

- Five steps:
  - 1. Generate the whole game tree, down to terminal states
  - 2. Apply the utility function to each terminal state to get its value
  - 3. Use this utility value of each terminal to determine the utility value of its parent nodes
  - 4. Continue backing up the values from the leaf nodes towards the root, one layer at a time
  - 5. Eventually we will reach the root of the tree. Now MAX must choose the root that maximises the utility value. This is called the minimax decision.



#### Minimax Algorithm: Pseudocode

MiniMax-Decision( game ):

for each action in actions( game ):
 state = apply( action, game )
 value[ action ] = MiniMax-Value( state, game)
 return action with the highest value[ action ]

MiniMax-Value( state, game ):
 if state == gameOver: // is a leaf node
 return utility-value( state )

else if state == maxNode: // MAX's move
return highest MiniMax-Value of successors( state, game )

else: // MIN's move

return lowest MiniMax-Value of successors( state, game )

#### Minimax Algorithm: Properties

- If the maximum depth of the tree is *m*, and there are *b* legal moves at each point, then the time complexity is O( b<sup>m</sup> )
  - Impractical for real games
- Depth-first search algorithm
- Implementation uses <u>recursion</u> instead of a queue
- Space requirements are linear in *m* and *b*
- Algorithm is basis for more realistic methods
- Basis for mathematical analysis of games

#### Overcoming Impracticalities

- Minimax assumes that a program must search all the way to terminal states
- This isn't practical
- Shannon proposed that program should cut off the search earlier and apply a <u>heuristic evaluation function</u>
- Minimax is altered in two ways:
  - 1. Utility function replaced by evaluation function EVAL
  - 2. Terminal test is replaced by cutoff test CUTOFF-TEST

## **Evaluation Function**

- <u>Estimates</u> expected utility of the game from a given position
  - Not new, take chess for example with its material values of pieces
- Quality of game-playing program dependent upon evaluation function
  - How do we measure quality?

#### Measuring Quality of Evaluation Function

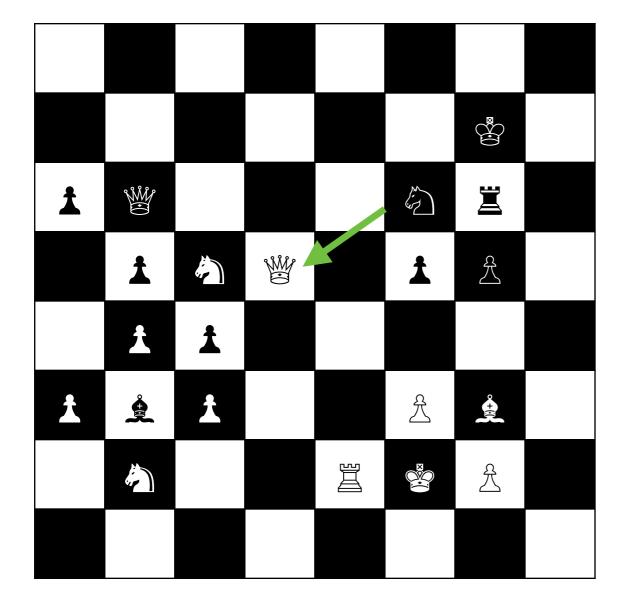
- 1. EVAL must agree with utility on terminal states
- 2. EVAL must not take too long
- 3. EVAL must reflect chances of winning

# Cutting Off Search

- Set a depth limit depth-limited search
- Depth is chose to ensure game does not take to long
- Iterative deepening is a more robust approach
- When time runs out, program returns move selected by the deepest completed search

#### Negative Consequence of Cutting Off Search

• Consider material advantage of chess:



Suppose search reaches limit at following position

EVAL(White) = 28EVAL(Black) = 25

- White ahead by a knight
- Black to move
- Black captures white queen
- No loss in return
- In reality, black gains advantage
- Evaluation function does not reflect this

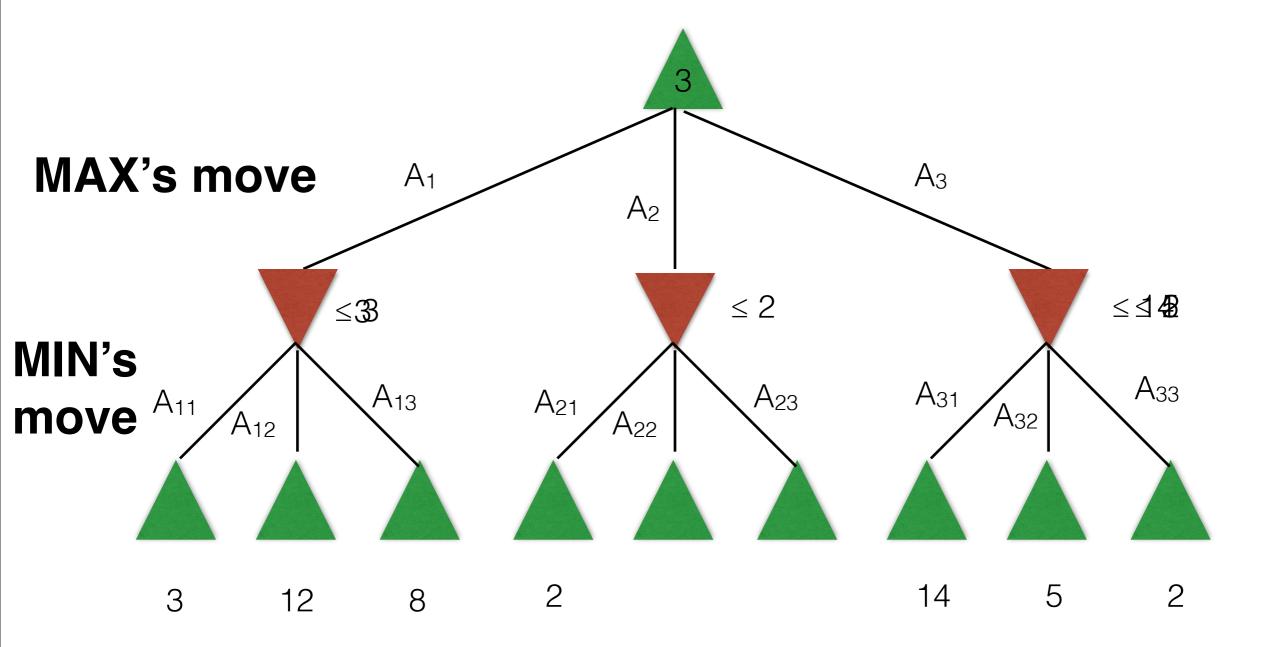
# Pruning the Search Tree

- Take our chess example:
  - One can search ~1000 moves per second
  - If we take 150 seconds per move we can look at 150,000 positions
  - Chess has a branching factor of ~35
    - We will only be able to look ahead 3 or 4 ply
    - Average humans plan ahead 6 to 8 ply

## Alpha-beta Pruning

- Returns the same move as minimax,
  - <u>Prunes</u> branches that cannot possibly influence the final decision

### Alpha-beta Pruning



#### Alpha-beta Pruning: General Principle

- Consider a node *n* in the tree
- If a player has a better choice *m* either at the parent node of *n* or at any point further up, then *n* will never be reached in actual play
- So once we know enough about *n* to reach this conclusion, we prune it.

## Summary

- Search process in games
- Evaluation function for moves in a game
- Pruning branches of a search tree